## **Prior and Posterior Distributions**

Often, we consider a parameter as a fixed, but unknown quantity. But there are many times when we have some incomplete information about its value. Perhaps we have observed several similar experiments in the past, giving us a range of plausible values for the parameter. Or maybe we have some educated guesses about the parameter based on theory and belief. In these cases, it makes sense to give a distribution to the possible values for the parameter and treat it as a random variable.

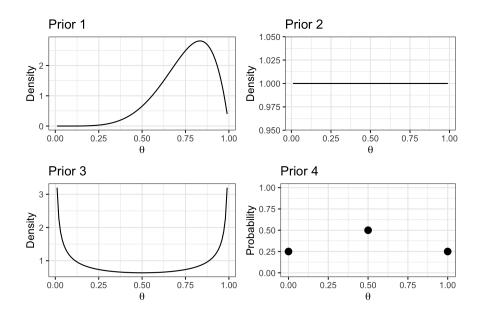
**Def:** The distribution of a parameter  $\theta$  before observing any data is called the **prior distribution** of the parameter. Often, we write the prior distribution for  $\theta$  as  $\xi(\theta)$ , which denotes the PDF if  $\theta$  is continuous and the PMF if  $\theta$  is discrete.

**Ex 1:** Consider a deck containing 100 red and black cards, where a proportion  $\theta$  of them are black. A sample of 10 cards are taken with replacement, and the number of black cards X is recorded.

Without looking in the deck, the value of  $\theta$  is unknown. We can model our uncertainty by treating  $\theta$  as a random variable and can consider the prior distribution of this variable.

The prior distribution represents a model of our own (subjective) personal beliefs about the value of  $\theta$ . Several (infinitely many!) different prior distributions are possible, and each represents different beliefs.

Consider the following four prior distributions. What beliefs do each distributions represent?



Before preceding, we need to formalize some notation and conventions:

Suppose X is a random variable whose distribution depends on the value of unknown parameter  $\theta$ . Often, we are interested in the conditional distribution of X given  $\theta$ , and write  $f(x|\theta)$  to denote the conditional PMF or PDF of X given the value of  $\theta$ , using the same symbol f to denote PMF or PDF regardless of whether X is discrete or continuous.

In many cases, we will collect a sample of data  $\mathbf{X} = (X_1, \ldots, X_n)$ , all of which are conditionally independent given  $\theta$  and have the same conditional PMF or PDF f given  $\theta$ . In this case, the conditional joint PMF or PDF of  $\mathbf{X}$  given  $\theta$  is

$$f(\mathbf{x}|\theta) = f(x_1|\theta)f(x_2|\theta)\cdots f(x_n|\theta)$$

**Note:** While each of the  $X_i$  have the same conditional PMF/PDF f,

$$f(\mathbf{x}|\theta) \neq [f(x|\theta)]^n$$

because each of the PMF/PDFs in the product are evaluated for a different variable  $x_i$ .

**<u>Ex 2</u>**: In the card deck example, what is the conditional PMF of X when  $\theta = \frac{1}{100}$ ? How does this change for different values of  $\theta$ ?

Probability ends and Statistics begins with the collection of data. Based on an observed sample, we may need to update our beliefs about a parameter. For example, if we were observing several flips of a coin, which *a priori* we believed either to be fair or two-head (with equal probability), and noticed that the first first 10 flips were all heads, it wouldn't be reasonable to continue to believe it just as likely the coin is fair as it is two-headed.

**Def:** Consider a statistical model with parameter  $\theta$  and random vector **X**. The conditional distribution of  $\theta$  given **X** = **x** is called the **posterior distribution** of  $\theta$  and denoted  $\xi(\theta | \mathbf{x})$  (where we interpret this as a PMF if  $\theta$  is discrete and a PDF if  $\theta$  is continuous).

But how should we find the posterior distribution? Note that our statistical model supplies the conditional distribution of  $\mathbf{X}$  given  $\theta$ . And by assumption, we have a prior distribution for  $\theta$ . We can then use Bayes' Theorem to get the posterior distribution!

<u>**Thm:**</u> Suppose that *n* random variables  $X_1, \ldots, X_n$  are iid with common distribution  $f(x|\theta)$ . Suppose further that  $\theta$  has prior distribution  $\xi(\theta)$ . Then the posterior distribution of  $\theta$  given  $\mathbf{X} = \mathbf{x}$  is

$$\xi(\theta \,|\, \mathbf{x}) = \frac{f(\mathbf{x}|\theta)\xi(\theta)}{g_n(\mathbf{x})} = \frac{f(x_1|\theta)\cdots f(x_n|\theta)\xi(\theta)}{g_n(\mathbf{x})}$$

where  $g_n$  is the marginal joint distribution of **X**.

*Proof.* Bayes' Theorem (either in continuous or discrete form).

**Ex 3:** Suppose we draw cards from the deck one-by-one with replacement until we draw 1 black card, and count the number of red cards X until this occurs. If the proportion of black cards is  $\theta$ , then  $X|\theta \sim \text{Geom}(\theta)$ .

One plausible prior distribution might be  $\theta \sim \text{Beta}(2,2)$ ; this distribution has mean of  $E[\theta] = \frac{1}{2}$ , and has a density that increases from  $\theta = 0$  to  $\theta = 0.5$ , and then decreases from  $\theta = 0.5$  to  $\theta = 1$ . The PMF for  $\theta$  is

$$\xi(\theta) = 6\theta(1-\theta)$$

Suppose we then draw x red cards before our first black card. What is the posterior distribution of  $\theta$ ?

Solution. The conditional PMF of X is

$$f(x|\theta) = (1-\theta)^x \theta \quad x \in \{0, 1, \dots\}$$

and so

$$f(x,\theta) = f(x|\theta)\xi(\theta) = (1-\theta)^x \theta \cdot 6\theta(1-\theta) = 6\theta^2(1-\theta)^{x+1}$$

Thus, the marginal density g of X is

$$\int_{0}^{1} f(x,\theta) \, d\theta = \int_{0}^{1} 6\theta^{2} (1-\theta)^{x+1} \, d\theta$$

But we recognize integrand from the Beta(3, x + 2) distribution:

$$1 = \int_0^1 \frac{\Gamma(x+5)}{\Gamma(3)\Gamma(x+2)} \theta^{3-1} (1-\theta)^{x+2-1} d\theta$$

And so

$$g(x) = \int_0^1 6\theta^2 (1-\theta)^{x+1} \, d\theta = 6 \frac{\Gamma(3)\Gamma(x+2)}{\Gamma(x+5)}$$

Therefore, the posterior distribution of  $\theta$  is

$$\xi(\theta \mid x) = \frac{f(x|\theta)\xi(\theta)}{g(x)} = \frac{6\theta^2 (1-\theta)^{x+1}}{6\frac{\Gamma(3)\Gamma(x+2)}{\Gamma(x+5)}} = \frac{\Gamma(x+5)}{\Gamma(3)\Gamma(x+2)}\theta^2 (1-\theta)^{x+1}$$

which is precisely the Beta(3, x + 2) distribution! Note that the posterior distribution of  $\theta$  depends on the observe value of x.

## Class Activity

1. Recall that if  $Y \sim \text{Beta}(a, b)$ , then

 $E[Y] = \frac{a}{a+b} \qquad \operatorname{Var}(Y) = \frac{ab}{(a+b)^2(a+b+1)}$ 

Compare the expectation and variance of the prior and posterior distributions for  $\theta$ .

- 2. Plot the posterior mean and posterior variance as functions of x. Describe any trends you observe, and discuss why these trends make intuitive sense in the context of the model.
- 3. Plot the prior PDF, as well as the posterior PDF for a variety of values of x. What trends do you observe?

## The Likelihood Function

In the preceding posterior distribution calculation, that we didn't **actually** need to calculate g! Note that g(x) is the marginal density of X, so while it IS a function of x, it doesn't contain  $\theta$ . Because we are conditioning on X, we are treating x as a constant, and so g is also constant with respect to  $\theta$ .

We know that  $\xi(\theta | x)$  is probability density, so must integrate to 1. So if we can identify a probability distribution (as function of  $\theta$ ) proportional to  $f(x|\theta)\xi(\theta)$ , this must be the distribution of  $\xi(\theta | x)$ , and g is simply the constant needed so this integrates to 1.

As a result, we often write

$$\xi(\theta \mid x) \propto f(x|\theta)\xi(\theta)$$

and ignore g.

**Note:** In the previous discussion, we considered a simplified case where collect a single observation X. But in practice, we will often collect a sample of n observations  $\mathbf{X} = (X_1, X_2, \dots, X_n)$ .

In this case, the joint distribution  $g_n(x_1, \ldots, x_n)$  of  $X_1, \ldots, X_n$  is still constant with respect to  $\theta$ , and so we can still identify the name of the posterior distribution  $\xi(\theta | \mathbf{x})$  just by looking at  $f_n(\mathbf{x}|\theta)\xi(\theta)$  and write

$$\xi(\theta \,|\, \mathbf{x}) \propto f_n(\mathbf{x}|\theta)\xi(\theta)$$

Originally, we considered the function  $f_n(\mathbf{x} | \theta)$  as the conditional distribution of  $\mathbf{x}$ , given fixed value of  $\theta$ . But if we think of the **data** as fixed, then this is a function of  $\theta$ .

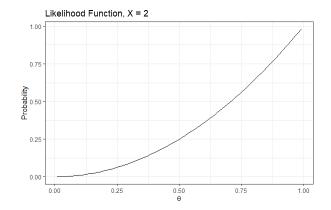
**<u>Def:</u>** The likelihood function of the observation  $\mathbf{x}$  is the conditional PMF  $f(\mathbf{x}|\theta)$  viewed as a function of  $\theta$  for fixed  $\mathbf{x}$ . Sometimes it is written as  $\mathcal{L}(\theta|\mathbf{x})$  to emphasize that it is a function of  $\theta$  for fixed  $\mathbf{x}$ .

The likelihood function should **not** be viewed as a PMF or PDF.

**<u>Ex 4</u>**: Suppose we flip a coin twice, with probability  $\theta$  of heads; let X be the number of heads obtained. What is the likelihood function for X = 2? What does the graph look like? Does the likelihood function integrate to 1? What does the likelihood function look like for X = 1?

Solution. The likelihood function for X = 2 is

$$\mathcal{L}(\theta|2) = f(2|\theta) = P(X=2|\theta) = {\binom{2}{2}}\theta^2(1-\theta)^0 = \theta^2 \qquad \theta \in (0,1)$$



Note

$$\int_0^1 \mathcal{L}(\theta|2) \, d\theta = \int_0^1 \theta^2 \, d\theta = \frac{1}{3}$$

For X = 1, the likelihood function is

$$\mathcal{L}(\theta|1) = f(1|\theta) = P(X=1|\theta) = {\binom{2}{1}}\theta^{1}(1-\theta)^{1} = 2\theta(1-\theta) \qquad \theta \in (0,1)$$

